

A beacon is a device that serves as a goodwill gesture to assist with navigation and to provide a warning sign of impending danger. In a similar way, "the beacon engineering consortium" serves to assist those who are adrift amid a sea of career choices. The consortium provides tangible examples of engineering challenges, opportunities, entrepreneurship, projects and practices to illuminate a pathway of safe passage for students and educators, and for existing and aspiring business owners. The consortium also serves as a warning sign to provide awareness of impending danger of substandard engineering practices and for identifying inappropriate career preparation.

Real-time robot control started as a master's degree project in 1989 and as computer training class at a tutorial center in Redlands CA in 1995. I took this job because I was laid off from my aerospace job and I needed the extra money. The section on "Robomotion" in the previous link moves a virtual robot with keyboard keystrokes. This evolved to computer mouse control of a virtual robot, then to laser distance meter control of a virtual robot.

In 1989, as part of a master's degree project, I developed <u>software to control a four-legged robot while walking on level ground</u>. I thought of ways to make it walk on uneven ground. Using the laser distance meter for "hand-eye coordination" was the solution. I integrated the laser guided idea for general robot control along with the computer mouse control as part of a patent in 2012. Now, <u>the concept is being considered at NSF as an alternative to exo-skeleton robot control</u> that now dominates the medical robotics industry.

The exoskeleton is similar to a teacher with a laser pointer in his/her hand. The laser positioner system is like a transit construction tool pointing to the same location.

# **Engineering Progress Steps**

## Five P's of Progress in Engineering



## Purpose

Thumb is strongest finger What is your main objective?

#### Plan

Index finger points to direction Make plans to point to objectives

## Preparation

Middle is longest finger Prep takes longest time Procure: Gather resources

Prototype: Picture while pretending progress towards purpose

Partition duties

#### Practice

Ring finger is similar length as index Practice your planned activities

## Progress

Little finger is smallest

Progress happens little by little, not by leaps and bounds

Five adages are evident from image above:

- 1. Necessity is the mother of invention (Purpose)
- 2. If you fail to plan, you plan to fail (Plan)
- 3. Measure twice, cut once (preparation + opportunity=success)
- 4. Practice makes progress (as opposed to perfect)
- 5. Progress happens little by little (See fifth phase below in graphic)

Jerry